Efficient Algorithms for Richer Formalisms: Parsing and Machine Translation

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My PhD research has been on the algorithmic and formal aspects of computational linguistics, esp. in the areas of parsing and machine translation. I am interested in developing efficient algorithms for formalisms with rich expressive power, so that we can have a better modeling of human languages without sacrificing efficiency. In doing so, I hope to help integrating more linguistic and structural knowledge with modern statistical techniques, and in particular, for syntax-based machine translation (MT) systems.

Among other projects, I have been working on *k*-best parsing, synchronous binarization, and syntax-directed translation.

1 *k*-best Parsing and Hypergraphs

NLP systems are often cascades of several modules, e.g., part-of-speech tagging, then syntactic parsing, and finally semantic interpretation. It is often the case that the 1-best output from one module is not always optimal for the next module. So one might want to postpone some disambiguation by propagating k-best lists (instead of 1-best solutions) to subsequent phases, as in joint parsing and semantic role-labeling (Gildea and Jurafsky, 2002). This is also true for reranking and discriminative training, where the k-best list of candidates serves as an approximation of the full set (Collins, 2000; Och, 2003; McDonald et al., 2005). In this way we can optimize some complicated objective function on the k-best set, rather than on the full search space which is usually exponentially large.

Previous algorithms for k-best parsing (Collins, 2000; Charniak and Johnson, 2005) are either suboptimal or slow and rely significantly on pruning techniques to make them tractable. So I codeveloped several fast and exact algorithms for kbest parsing in the general framework of directed monotonic hypergraphs (Huang and Chiang, 2005). This formulation extends and refines Klein and Manning's work (2001) by introducing *monotonic*

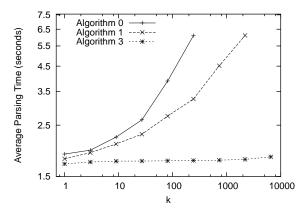


Figure 1: Average parsing speed on the Section 23 of Penn Treebank (Algorithms 0, 1, and 3, log-log).

weight functions, which is closely related to the optimal subproblem property in dynamic programming.

We first generalize the classical 1-best Viterbi algorithm to hypergraphs, and then present four k-best algorithms, each improving its predessor by delaying more work until necessary. The final one, Algorithm 3, starts with a normal 1-best search for each vertex (or *item*, as in deductive frameworks), and then works backwards from the target vertex (final item) for its 2nd, 3rd, ..., kth best derivations, calling itself recursively only on demand, being the laziest of the four algorithms. When tested on top of two state-of-the-art systems, the Collins/Bikel parser (Bikel, 2004) and Chiang's CKY-based Hiero decoder (Chiang, 2005), this algorithm is shown to have very little overhead even for quite large k (say, 10^6) (See Fig. 1 for experiments on Bikel parser).

These algorithms have been re-implemented by other researchers in the field, including Eugene Charniak for his *n*-best parser, Ryan McDonald for his dependency parser (McDonald et al., 2005), Microsoft Research NLP group (Simon Corston-Oliver and Kevin Duh, p.c.) for a similar model, Jonathan Graehl for the ISI syntax-based MT decoder, David A. Smith for the Dyna language (Eisner et al., 2005), and Jonathan May for ISI's tree automata package Tiburon. All of these experiments confirmed the findings in our work.

2 Synchronous Binarization for MT

Machine Translation has made very good progress in recent times, especially, the so-called "phrasebased" statistical systems (Och and Ney, 2004). In order to take a substantial next-step it will be necessary to incorporate several aspects of syntax. Many researchers have explored syntax-based methods, for instance, Wu (1996) and Chiang (2005) both uses binary-branching synchronous context-free grammars (SCFGs). However, to be more expressive and flexible, it is often easier to start with a general SCFG or tree-transducer (Galley et al., 2004). In this case, *binarization* of the input grammar is required for the use of the CKY algorithm (in order to get cubic-time complexity), just as we convert a CFG into the Chomsky Normal Form (CNF) for monolingual parsing. For synchronous grammars, however, different binarization schemes may result in very different-looking chart items that greatly affect decoding efficiency. For example, consider the following SCFG rule:

(1)
$$S \rightarrow NP^{(1)} VP^{(2)} PP^{(3)}, NP^{(1)} PP^{(3)} VP^{(2)}$$

We can binarize it either left-to-right or right-to-left:

$$egin{array}{ccc} \mathbf{S} &
ightarrow & V_{\mathrm{NP-PP}} \, \mathbf{VP} & \mathbf{S} &
ightarrow & \mathbf{NP} \, V_{\mathrm{PP-VP}} \ V_{\mathrm{NP-PP}} &
ightarrow & \mathbf{NP} \, \mathbf{PP} & \mathbf{Or} & V_{\mathrm{PP-VP}} &
ightarrow & \mathbf{PP} \, \mathbf{VP} \end{array}$$

The intermediate symbols (e.g. $V_{\text{PP-VP}}$) are called *vir*tual nonterminals. We would certainly prefer the right-to-left binarization because the virtual nonterminal has consecutive span (see Fig. 2). The left-toright binarization causes discontinuities on the target side, which results in an exponential time complexity when decoding with an integrated *n*-gram model.

We develop this intuition into a technique called *synchronous binarization* (Zhang et al., 2006) which binarizes a synchronous production or tree-tranduction rule on both source and target sides *simultaneously*. It essentially converts an SCFG into an equivalent ITG (the synchronous extension of CNF) if possible. We reduce this problem to the binarization of the permutation of nonterminal symbols between the source and target sides of a synchronous rule and devise a linear-time algorithm

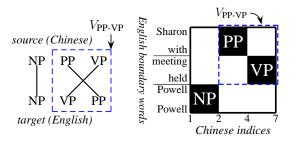


Figure 2: The alignment pattern (left) and alignment matrix (right) of the SCFG rule.

system	BLEU
monolingual binarization	36.25
synchronous binarization	38.44

Table 1: Synchronous vs. monolingual binarization in terms of translation quality (BLEU score).

for it. Experiments show that the resulting rule set significantly improves the speed and accuracy over monolingual binarization (see Table 1) in a stateof-the-art syntax-based machine translation system (Galley et al., 2004). We also propose another trick (hook) for further speeding up the decoding with integrated n-gram models (Huang et al., 2005).

3 Syntax-Directed Translation

Syntax-directed translation was originally proposed for compiling programming languages (Irons, 1961; Lewis and Stearns, 1968), where the source program is parsed into a syntax-tree that guides the generation of the object code. These translations have been formalized as a synchronous context-free grammar (SCFG) that generates two languages simultaneously (Aho and Ullman, 1972), and equivalently, as a top-down tree-to-string transducer (Gécseg and Steinby, 1984). We adapt this syntaxdirected transduction process to statistical MT by applying stochastic operations at each node of the source-language parse-tree and searching for the best derivation (a sequence of translation steps) that converts the whole tree into some target-language string (Huang et al., 2006).

3.1 Extended Domain of Locality

From a modeling perspective, however, the structural divergence across languages results in nonisomorphic parse-trees that are not captured by SCFGs. For example, the S(VO) structure in English is translated into a VSO order in Arabic, an instance of *complex re-ordering* (Fig. 4).

To alleviate this problem, grammars with richer expressive power have been proposed which can grab larger fragments of the tree. Following Galley et al. (2004), we use an extended tree-to-string transducer (**xRs**) with multi-level left-hand-side (LHS) trees.¹ Since the right-hand-side (RHS) string can be viewed as a flat one-level tree with the same nonterminal root from LHS (Fig. 4), this framework is closely related to STSGs in having extended domain of locality on the source-side except for remaining a CFG on the target-side. These rules can be learned from a parallel corpus using English parsetrees, Chinese strings, and word alignment (Galley et al., 2004).

3.2 A Running Example

Consider the following English sentence and its Chinese translation (note the reordering in the passive construction):

(2) the gunman was killed by the police.

qiangshou bei jingfang jibi 。 [gunman] [passive] [police] [killed].

Figure 3 shows how the translator works. The English sentence (a) is first parsed into the tree in (b), which is then recursively converted into the Chinese string in (e) through five steps. First, at the root node, we apply the rule r_1 which preserves the top-level word-order and translates the English period into its Chinese counterpart:

(r_1) S (x_1 :NP-C x_2 :VP PUNC (.)) $\rightarrow x_1 x_2$.

Then, the rule r_2 grabs the whole sub-tree for "the gunman" and translates it as a phrase:

(r_2) NP-C (DT (the) NN (gunman)) \rightarrow qiangshou

Now we get a "partial Chinese, partial English" sentence "*qiangshou* VP $_{\circ}$ " as shown in Fig. 3 (c). Our recursion goes on to translate the VP sub-tree. Here we use the rule r_3 for the passive construction: (a) the gunman was killed by the police .

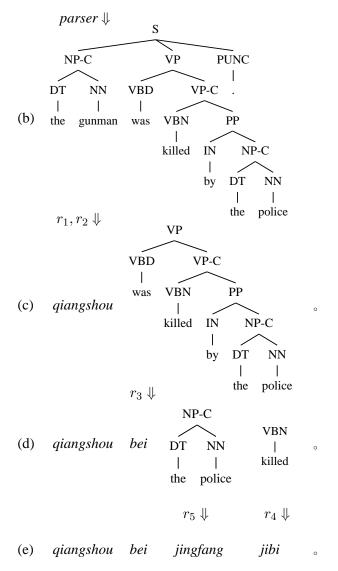


Figure 3: A synatx-directed translation process.

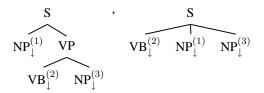


Figure 4: An example of complex re-ordering.

¹we will use LHS and source-side interchangeably (so are RHS and target-side). In accordance with our experiments, we also use English and Chinese as the source and target languages, opposite to the Foreign-to-English convention of Brown et al. (1993).

$$(r_{3}) \begin{array}{c} VP \\ VBD \\ (r_{3}) \end{array} \begin{array}{c} VP-C \\ | \\ (r_{3}) \end{array} \begin{array}{c} VP-C \\ | \\ N \\ (r_{2}:NP-C \\ | \\ by \end{array} \end{array} \rightarrow bei \ x_{2} \ x_{1}$$

which captures the fact that the agent (NP-C, "the police") and the verb (VBN, "killed") are always inverted between English and Chinese in a passive voice. Finally, we apply rules r_4 and r_5 which perform phrasal translations for the two remaining subtrees in (d), respectively, and get the completed Chinese string in (e).

3.3 Translation Algorithm

Given a fixed parse-tree τ^* , the search for the best derivation (as a sequence of conversion steps) can be done by a simple top-down traversal (or depthfirst search) from the root of the tree. With memoizationm, we get a dynamic programming algorithm that is guaranteed to run in O(n) time where n is the length of the input string, since the size of the parsetree is proportional to n. Similar algorithms have also been proposed for dependency-based translation (Lin, 2004; Ding and Palmer, 2005).

I am currently performing large-scale experiments on English-to-Chinese translation using the **xRs** rules. We are not doing the usual direction of Chinese-to-English partly due to the lack of a sufficiently good Chinese parser. Initial results show promising translation quality (in terms of BLEU scores) and fast translation speed.

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