A Direct Syntax-Driven Reordering Model for Phrase-Based Machine Translation

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Abstract

This paper presents a direct word reordering model with novel syntax-based features for statistical machine translation. Reordering models address the problem of reordering source language into the word order of the target language. IBM Models 3 through 5 have reordering components that use surface word information but very little context information to determine the traversal order of the source sentence. Since the late 1990s, phrase-based machine translation solves much of the local reorderings by using phrasal translations. The problem of long-distance reordering has become a central research topic in modeling distortions. We present a syntax driven maximum entropy reordering model that directly predicts the source traversal order and is able to model arbitrarily long distance word movement. We show that this model significantly improves machine translation quality.

1 Introduction

Machine translation reordering models model the problem of the word order when translating a source language into a target language. For example in Spanish and Arabic, adjectives often come after the nouns they modify whereas in English modifying adjectives usually precede the nouns. When translating Spanish or Arabic into English, the position of the adjectives need to be properly reordered to be placed before the nouns to make fluent English.

In this paper, we present a word reordering model that models the word reordering process in translation. The paper is organized as follows. §2 outlines previous approaches to reordering. §3 details our model and its training and decoding process. §4 discusses experiments to evaluate the model and §5 presents machine translation results. §6 is discussion and conclusion.

2 Previous Work

The word reordering problem has been one of the major problems in statistical machine translation (SMT). Since exploring all possible reorderings of a source sentence is an NP-complete problem (Knight 1999), SMT systems limit words to be reordered within a window of length k. IBM Models 3 through 5 (Brown et.al. 1993) model reorderings based on surface word information. For example, Model 4 attempts to assign target-language positions to source-language words by modeling $d(j \mid i, l, m)$ where j is the target-language position, i is the source-language position, l and m are respectively source and target sentence lengths. These models are not effective in modeling reorderings because they don't have enough context and lack structural information.

Phrase-based SMT systems such as (Koehn et.al. 2003) move from using words as translation units to using phrases. One of the advantages of phrase-based SMT systems is that local reorderings are inherent in the phrase translations. However, phrase-based SMT systems capture reordering instances and not reordering phenomena. For example, if the Arabic phrase "*the car red*" and its English translation "the red car' is seen in the training data, phrase-based SMT is able to produce the correct English for the Arabic 'the car red'. However it will not be able to produce 'the blue car' for the Arabic '*the car blue*' if the training data does not contain this phrase pair. Phrases do not capture the phenomenon that Arabic adjectives and nouns need to be reordered. Another problem with phrase-based SMT is the problem of long-range reorderings. Recent work on reordering has been focusing on capturing general reordering

phenomena (as opposed to instances) and on solving long-range reordering problems.

(Al-onaizan et.al. 2006) proposes 3 distortion models, the inbound, outbound, and pair models. They together model the likelihood of translating a source word at position i given that the source word at position j has just been translated. These models perform better than n-gram based language models but are limited in their use of only the surface strings.

Instead of directly modeling the distance of word movement, phrasal level reordering models model how to move phrases, also called *orientations*. Orientations typically apply to adjacent phrases. Two adjacent phrases can be either placed monotonically (sometimes called *straight*) or swapped (non-monotonically or *inverted*). Early orientation models do not use lexical contents such as (Zens et. al., 2004). More recently, (Xiong et.al. 2006; Zens 2006; Och et. al, 2004; Tillmann, 2004; Kumar et al., 2005, Ni et al., 2009) all presented models that use lexical features from the phrases to predict their orientations. These models are very powerful in predicting local phrase placements. More recently (Galley et.al. 2008) introduced a hierarchical orientation model that captures some non-local phrase reorderings by a shift reduce algorithm. Because of the heavy use of lexical features, these models tend to suffer from data sparseness problems. Another limitation is that these models are restricted to reorderings with no gaps and phrases that are adjacent.

We present a probabilistic reordering model that models directly the source translation sequence and explicitly assigns probabilities to the reorderings of the source input with no restrictions on gap, length or adjacency. This is different from the approaches of pre-order such as (Xia and McCord 2004; Collins et.al. 2005; Kanthak et. al. 2005; Li et. al., 2007). Although our model can be used to produce top N pre-ordered source, the experiments reported here do not use the model in the pre-order mode. Instead, the reordering model is used to generate a reorder lattice which encodes many reorderings and their costs (negative log probability). This reorder lattice is independent of the translation decoder. In principle, any decoder can use this lattice for its reordering needs. We have integrated the reorder lattice into a phrase-based. The experiments reported here are from the phrase-based decoder.

We present the reordering model based on maximum entropy models. We then describe the syntactic features in the context of Chinese to English translation.

3 Maximum Entropy Reordering Model

The model takes a source sequence of length n:
$$S = [s_1, s_2, ...s_n]$$
and models its translation or *visit* order according to the target language:
$$V = [v_1, v_2, ...v_n]$$
where v_j is the source position for target position j. For example, if the 2nd source word is to be translated first, then $v_1 = 2$. We find V such that
$$\arg \max_{V \in \{v\}} p(V \mid S) \qquad (1)$$

$$= \max \prod_{j=1}^{n} p(v_j \mid S, v_{1...}v_{j-1}) \qquad (2)$$

In equation (1) {υ} is the set of possible visit orders. We want to find a visit order V such that the probability p(V|S) is maximized. Equation (2) is a component-wise decomposition of (1).

Let
$$f = v_j \; and \; h = (S, v_1...v_{j-1})$$
We use the maximum entropy model to estimate equation (2):
$$p(f \mid h) = \frac{1}{Z(h)} \exp(\sum_k \lambda_k \phi_k (f,h)) \quad (3)$$

where $Z(h)$ is the normalization constant
$$Z(h) = \sum_f \exp \sum_k \lambda_k \phi_k (f,h) \qquad (4)$$

In equation (3), $\phi_k(f, h)$ are binary-valued features. During training, instead of exploring all possible permutations, samples are drawn given the correct path only.

3.1 Feature Overview

Most of our features $\phi_k(f, h)$ are syntax-based. They examine how each parse node is reordered during translation. We also have a few non-syntax features that inspect the surface words and part-of-speech tags. They complement syntax features by capturing lexical dependencies and guarding against parsing errors. Instead of directly model-

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ing the absolute source position v_j, we model the jump from the last source position v_{j-1}. All features share two common components: j (for *jump),* and *cov* (for *coverage*). *Jumps* are bucketed and capped at 4 to prevent data sparsity. *Coverage* is an integer indicating the visiting status of the words between the jump. Coverage is 0 if none of the words was visited prior to this step, 1 if all were visited, and 2 if some but not all were visited. (j, cov) are present in all features and are removed from the descriptions below. A couple of features use a variation of *Jump* and *Coverage*. These will be described in the feature description.

3.2 Parse-based Syntax Features

We use the sentence pair in Figure 1. as a working example when describing the features. Shown in the figure are a Chinese-English parallel sentence pair, the word alignments between them, and

ure 1. If a target is aligned to more than one source, we assume the visit order is left to right. In Figure 1, source words 2 and 8 are aligned to the English 'at' and we define the visit sequence to be 8 following 2.

Chinese and English differ in the positioning of the modifiers. In English, non-adjectival modifiers follow the object they modify. This is most prominent in the use of relative clauses and prepositional phrases. Chinese in contrast is a premodification language where modifiers whether adjectival, clausal or prepositional typically precede the object they modify. In Figure 1., the Chinese prepositional phrase PP (in *lightly shaded* box in the parse tree) spanning range [2,8] precedes the verb phrase VP2 at positions [9,10]. These two phrases are swapped in English as shown by the two lightly shaded boxes in the alignment grid. The relative clause CP (in *dark*
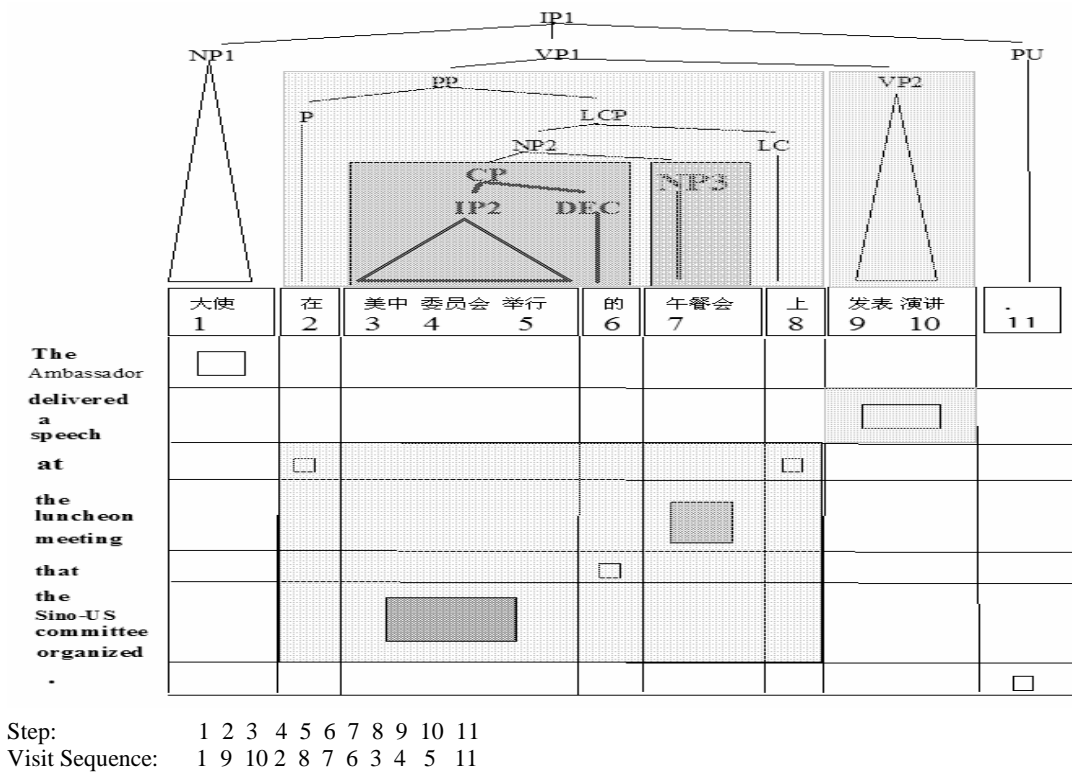

Figure 1. A Chinese-English Parallel Sentence with Chinese Parse

the Chinese parse tree. The parse tree is simplified. Some details such as part-of-speech tags are omitted and denoted by triangles. The first step is to determine the source visit sequence from the word alignment, also shown at the bottom of Fig-

shaded box in the parse tree) in Chinese spanning range [3,6] precedes the noun phrase NP3 at position 7 whereas these two phrases are again swapped in English.

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The phenomenon for the reordering model to capture is that node VP1's two children PP and VP2 (*lightly shaded*) need to be swapped regardless of how long the PP phrase is. This is also true for node NP2 whose two children CP and NP3 (*dark shaded*) need to be reversed.

Parse-based features model how to reorder the constituents in the parse by learning how to walk the parse nodes. For every non-unary node in the parse we learn such features as which of its child is visited first and for subsequent visits how to jump from one child to another. For the treelet VP1 → PP VP2 in Figure 1, we learn to visit the child VP2 first, then PP.

We now define the notion of '*node visit*'. When a source word s_i is visited at step j, we find its path to root from the leaf node denoted as $PathToRoot_i$. We say all the nodes contained in $PathToRoot_i$ are being visited at that step. Parse-based features are applied to every qualifying node in $PathToRoot_i$. Unary extensions do not qualify and are ignored. Since part-of-speech tags are unary branches, parse-based features apply from the lowest-level labels. Another condition depends on the jump and is discussed in section §3.4. All our features are encoded by a vector of integers and are denoted as ϕ (·) in this paper. We now describe the features.

3.2.1 First Child Features

The *first-child* feature applies when a node is visited for the first time. The feature learns which of the node's child to visit first. This feature learns such phenomena as translating the main verb first under a VP or translating the main NP first under an NP. The feature is defined as ϕ(*currentLabel, parentLabel, nthNode, j, cov)* where
currentLabel = label of the current parse node
parentLabel = label of the parent node
nthNode = an integer indicating the nth occurrence of the current node

In Figure 1, when source word 9 is visited at step 2, its *PathToRoot* is computed which is [VP2, VP1, IP1]. The *first-child* feature applied to VP2 is ϕ(VP2, VP1, 1, 4, 1) since
currentLabel = VP2; *parentLabel* = VP1;
nthChild = 1: VP2 is the 1st VP among its parent's children
j = 4: actual jump from 1 is 8 and is capped.

cov = 0: words in between the jump [1,9] are not yet visited at this step.
The semantics of this feature is that when a VP node is visited, the first VP child under it is visited first. This feature learns to visit the first VP first which is usually the head VP no matter where it is positioned or how many modifiers precede it.

3.2.2 Node Jump Features

This feature applies on all subsequent visits to the parse node. This feature models how to jump from one sibling to another sibling. This feature has these components: ϕ(*currentLabel, parentLabel, fromLable, nodeJump,cov)* where
fromLabel = the node label where the jump is from
nodeJump = node distance from that node
This feature effectively captures syntactic reorderings by looking at the node jump instead of surface distance jump. In our example, a *node-jump* feature for jumping from source 10 to 2 at step 4 at VP1 level is ϕ(PP, VP1, VP2, -1, 2) where
currentLabel = PP where source word 2 is under
parentLabel = VP1
fromLabel = VP2 where source word 10 is under
nodeJump = -1 since the jump is from VP2 to PP
cov = 2 because in between [2,10] word 9 has been visited and other words have not.

This feature captures the necessary information for the 'PP VP' reorderings regardless of how long the PP or VP phrase is.

3.2.3 Jump Over Sibling Features

To make a correct jump from one sibling to the other, siblings that are jumped over should also be considered. For example in Chinese, while jumping over a PP to cover a VP is a good jump, jumping over an ADVP to cover a VP may not be because adverbs in both Chinese and English often precede the verb they modify. The *jump-over-sibling* features help distinguish these cases. This feature's components are ϕ(*currentLabel, parentLabel, jumpOverSibling, siblingCov, j)* where *jumpOverSibling* is the label of the sibling that is jumped over and *siblingCov* is the coverage status of that sibling.

This feature applies to every sibling that is jumped over. At step 2 where the jump is from source 1 to 9, this feature at VP1 level is ϕ(VP2, VP1, PP, 0, 4) because PP is a sibling of VP2 and

is jumped over, PP is not covered at this step, and the jump is capped to be 4.

3.2.4 Back Jump Sibling Features

For every forward jump of length greater than 1, there is a backward jump to cover those words that were skipped. In these situations we want to know how far we can move forward before we must jump backward. The *back-jump-sibling* feature applies when the jump is backward (distance is negative) and inspects the sibling to the right. It generates $\phi(currentLabel, \quad rightSiblingCov, \quad j)$. When jumping from 10 to 2 at step 4, this feature is $\phi(PP, 1, -4)$ where -4 is the *jump* and *currentLabel* = PP where source word 2 is under *rightSiblingCoverage* = 1 since VP2 has been completed visited at this time. This feature learns to go back to PP when its right sibling (VP2) is completed.

3.2.5 Broken Features

Translations do not always respect the constituent boundaries defined by the source parse tree. Consider the fragment in Figure 2.
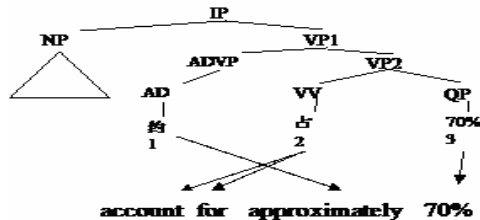

Figure 2. A '*Broken*' Tree

After the VV under VP2 is translated ("*account for*"), a transition is made to translate the ADVP ("*approximately*") leaving VP2 partially translated. We say that the node VP2 is *broken* at this step. This type of feature has been shown to be useful for machine translation (Marton & Resnik 2008). Here, *broken* features model the context under which a node is broken by observing the feature $\phi(curTag, prevTag, parentLabel, j, cov)$. For the transition of source word 2 to source word 1 in Figure 2, a broken feature applies at VP2: $\phi(AD, VV, VP2, -1, 1)$. This feature learns that a VP can be broken when making a jump from a verb (VV) to an adverb (AD).

3.3 Non-Parse Features

Non-parse features do not use or use less fine-grained information from the parse tree.

3.3.1 Barrier Features

Barrier features model the intuition that certain words such as punctuation should not move freely. This phenomenon has been observed and shown to be helpful in (Xiong et. al., 2008). We call these words *barrier* words. Barrier features are $\phi(barrierWord, cov, j)$. All punctuations are barrier words.

3.3.2 Number of Zero Islands Features

Although word reorderings can involve words far apart, certain jump patterns are highly unlikely. For example, the coverage pattern '1010101010' where every other source word is translated would be very improbable. Let the right most covered source word be the *frontier*. For every jump, the *number-of-zero-islands* feature computes the number of uncovered source islands to the left of the frontier. Additionally it takes into account the number of parse nodes in between. This feature is defined as $\phi(numZeroIslands, j, numParseNodesInBetween)$. The number of parse nodes is the number of maximum spanning nodes in between the jump. The jump at step 2 from source 1 to 9 triggers this number-zero-island feature $\phi(1, 4, 1)$. The source coverage status at step 2 is 10000000100 because the first source word has been visited and the current visit is source 9. All words in between have not been visited. There is 1 contiguous sequence of 0's between the first '1' and the last '1', hence the *numZeroIslands* = 1. There is one parse node PP that spans all the source words from 2 to 8, therefore the last argument to the feature is 1. If instead, the transition was from source 1 to 8, then there would be 2 maximum spanning parse nodes for source [2,7] which are nodes P and NP2. The feature would be $\phi(1, 4, 2)$. This feature discourages scattered jumps that leave lots of zero islands and jump over lots of parse nodes.

3.4 Training

Training the maximum entropy reordering model needs word alignments and source-side parses. We use hand alignments from LDC. The training data

statistics are shown in Table 1. We use the (Levy and Manning 2003) parser on Chinese.

Data	#Sentences	#Words
LDC2006E93	10,408	230,764
LDC2008E57	11,463	194,024

Table 1. Training Data

From the word alignments we first determine the source visit sequence. Table 2 details how the visit sequence is determined in various cases.

Alignment Type S-T	Visit Sequence
1-1	Left to right from target
m-1	Left to right from source
1-m	Left most target link
Ø	Attaches left

Table 2. Determining visit sequence

The first column shows alignment type from source (S) to target (T). 1-1 means one source word aligns to one target word. m-1 means many source words align to one target and vice versa. Ø means unaligned source words.

After the source visit sequence is decided, features are generated. Note that the height of the tree is not uniform for all the words. To preserve the structure and also alleviate the depth problem, we use the *lowest-level-common-ancestor* approach. For every jump, we generate features bottom up until we reach the node that is the common ancestor of the origin and the destination of the jump. In Figure 1 there is a jump from source 7 to 6 at step 7. The *lowest-level-common-ancestor* for source 6 and 7 is the node NP2 and features are generated up to the level of NP2. Features on this training data are shown in the second column in Table 5.

The MaxEnt model on this data is efficiently trained at 15 minutes per iteration (24 sentences/sec or 471 words/sec).

4 Experiments

4.1 Reorder Evaluation

To evaluate how accurate the reordering model is, we first compute its prediction accuracy. We choose the first 100 sentences from NIST MT03 as our test set for this evaluation. We manually word align them to the first set of reference using LDC annotation guidelines version 1.0 of April 2006.

An average of 73% of the training sentences contain unaligned source words and over 87% of the test sentences contain unaligned source words. The unaligned source words are mostly function words. Because the visit sequence of unaligned source words are determined not by truth but by heuristics (Table 2), they pose a problem in evaluation.

We thus evaluate the model by measuring the accuracy of its decision conditioned on true history. We measure performance on the model's top-N choices for N = 1,2, and 3. Results are in Table 3. The table also shows the accuracy of no reordering in the *Monotone* column.

Top-N	Accuracy	Monotone
1	80.56%	65.39%
2	90.66%	-
3	93.05%	-

Table 3. Reordering model performance

Figure 3 plots accuracy vs. MaxEnt training iteration. Accuracy starts low at 74.7% and reaches is highest at iteration 8 and fluctuates around 80.5% thereafter.
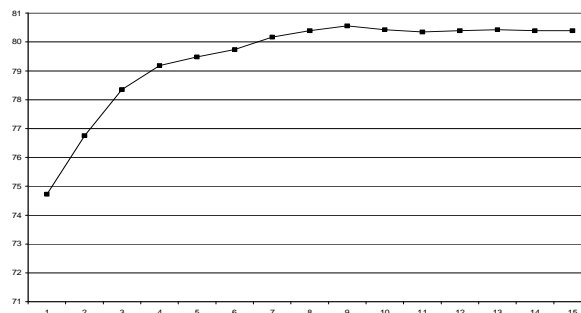

Figure 3. Accuracy vs. MaxEnt Training Iteration

We analyze 50 errors from the top-1 run. The errors are categorized and shown in Table 4.

Error Category	Percentage
Lexical	34%
Parse	30%
Model	20%
Reference	16%

Table 4. Error Analysis

'*Lexical*' errors are those that rise from lexical choice of source words. For example, an "ADVP VP" structure would normally be visited monotonically. However, in case of Chinese phrase '*so do*', they should be swapped. More than a third of the errors are of this nature. Errors in the *Refer-*

ence category are those that are marked wrong because of the particular English reference. The proposed reorderings are correct but they don't match the reference reorderings. Another 30% of the errors are due to parsing errors. The *Model* errors are due to two sources. One is the depth problem mentioned above. Local statistics for some very deep treelets overwhelm the global statistics and local jumps win over the long jumps in these cases. Another problem is the data sparseness. For example, the model has learned to reorder the 'PP VP' structure but there is not much data for 'PP ADVP VP'. The model fails to jump over PP into ADVP.

4.2 Feature Utility

We conduct ablation studies to see the utilities of each feature. We take the best feature set which gives the performance in Table 3 and takes away one feature type at a time. The results are in Table 5. The first row keeps all the features. The *Subtract* column shows performance after subtracting each feature while keeping all the other features. The *Add* column shows performance of adding the feature. Using just *first-child* features gets 75.97%. Adding *node-jump* features moves the accuracy to 78.40% and so on.

Features	#Features	Subtract	Add
-		80.56%	-
First Child	7,559	79.87%	75.97%
Node Jump	6,334	79.52%	78.40%
JumpOver Sib.	2,403	80.52%	79.00%
BackJump	602	80.48%	79.05%
Broken	15,183	80.30%	79.13%
Barrier	158	80.26%	79.22%
NumZ Islands	200	79.52%	80.56%

Table 5. Ablation study on features

5 Translation Experiments

5.1 Reorder Lattice Generation

The reordering model is used to generate reorder lattices which are used by machine translation decoders. Reorder lattices have been frequently used in decoding in works such as (Zhang et. al 2007, Kumar et.al. 2005, Hildebrand et.al. 2008), to name just a few. The main difference here is that our lattices encode probabilities from the reordering model and are not used to preorder the source.

The lattice contains reorderings and their cost (negative log probability). Figure 4 shows a reorder lattice example. Nodes are lattice states. Arcs store source word positions to be visited (translated) and their cost and they are delimited by comma in the figure. Lower cost indicates better choice. Figure 4 is much simplified for readability. It shows only the best path (highlighted) and a few neighboring arcs. For example, it shows source words 1, 2, and 8 are the top 3 choices at step 1. Position 1 is the best choice with the lowest cost of 0.302 and so on.
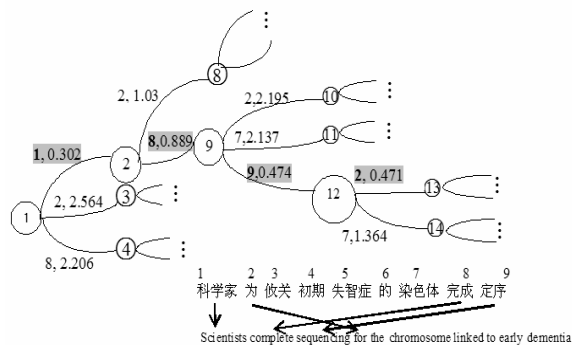

Figure 4. A lattice example

The sentence is shown at the bottom of the figure. The first part of the reference (true) path is indicated by the alignment which is source sequence 1, 8, 9, and 2. We see that this matches the lattice's top-1 choice.

Lattice generation takes source sentence and source parse as input. The lattice generation process makes use of a beam search algorithm. Every node in the lattice generates top-N next possible positions and the rest is pruned away. A coverage vector is maintained on each path to ensure each source word is visited exactly once. A wide beam width explores many source positions at any step and results in a bushy lattice. This is needed for machine translation because the parses are errorful. The structures that are hard for MT to reorder are also hard for parsers to parse. Labels critical to reordering such as CP are among the least accurate labels. Overall parsing accuracy is 83.63% but CP accuracy is 73.11%. We need a wide beam to include more long jumps to compensate the parsing errors.

5.2 Machine Translation

We run MT experiments on NIST Chinese-English test sets MT03-05. We compare the performance

of using distance-based reordering and using maximum entropy reordering lattices. The decoder is a log-linear phrase based decoder. Translation models are trained from HMM alignments. A smoothed 5-gram English LM is built on the English Gigaword corpus and English side of the Chinese-English parallel corpora. In the experiments, lexicalized distance-based reordering allows up to 9 words to be jumped over. MT performance is measured by BLEUr4n4 (Papineni et.al. 2001).

The test set statistics and experiment results are show in Table 6. Decoding with MaxEnt reorder lattices shows significant improvement for all conditions.

Data	#Segs	Lex Skip-9	Reord Lattice	Gain
MT03	919	0.3005	0.3315	+3.1
MT04	1788	0.3250	0.3388	+1.38
MT05	1082	0.2957	0.3236	+2.79

Table 6. MT results

Figures 5 shows an example from MT output with word alignments to the Chinese input. The MaxEnt reordering model correctly reorders two source modifiers at source positions 8 and 22. The Skip9 output reorders locally whereas the MaxEnt lattice output shows much more complex reorderings.

6 Conclusions

We present a direct syntax-based reordering model that captures source structural information. The model is capable of handling reorderings of arbitrary length. Long-range reorderings are essential in translation between languages with great word order differences such as Chinese-English and Arabic-English. We have shown that phrase based SMT can benefit significantly from such a reordering model.

The current model is not regularized and feature selection by thresholding the feature counts is quite primitive. Regularizing the model will prevent overfitting, especially given the small training data set. Regularization will also make the ablation study more meaningful.

The reordering model presented here aims at capturing structural differences between source and target languages. It does not have enough lexical features to deal with lexical idiosyncrasies.
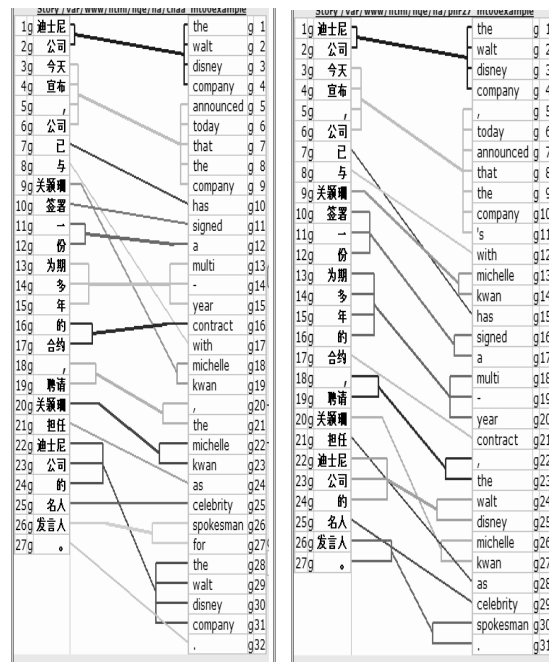

ME Lattice MT   Skip9 MT

Figure 5. MT comparison

Our initial attempt at adding lexical pair jump features $\phi(fromWord, toWord, j)$ has not proved useful. It hurt accuracy by 3% (from 80% to 77%). We see from Table 4 that 34% of the errors are due to source lexical choices which indicates the weakness of the current lexical features. Regularization of the model might also make a difference with the lexical features.

Reordering and word choice in translation are not independent of each other. We have shown some initial success with a separate reordering model. In the future, we will build joint models on reordering and translation. This approach will also address some of the reordering problems due to source lexical idiosyncrasies.

7 Acknowledgement

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